




PERSONAL INFORMATION	Stefano Panzieri	
		
		
		
	Sex Male Date of birth 17/12/1963 Nationality Italian	
CURRENT POSITION SSD (if applicable)	Full professor ING-INF/04 Automatica	
RESEARCH TOPICS / EXPERIENCES	<ul style="list-style-type: none"> ▪ Critical Infrastructures ▪ Robotics ▪ Networked Systems ▪ Smart Building ▪ Energy management 	
SCIENTIFIC / TECHNICAL QUALIFICATION (source: Scopus)	H-index:	22
	No. publications:	148
	No. citations:	1633
THEMATIC AREA KEYWORDS (it is possible to select one or more than one thematic area)	Energy transition:	Smart Buildings, Smart Cities, Active Demand, Energy Management, IoT
	Digital transition:	Cyber Security for Industrial/Building automation
	Bio-pharma & health:	-

EDUCATION AND TRAINING

1994/08/29	PhD System Engineering
1989/12/14	Laurea degree in Electronic Engineering

WORK EXPERIENCE

since 2019	Full Professor Automatic Control
	University ROMA TRE
2003-2019	Associate Professor
	University ROMA TRE
1996-2003	Assistant Professor
	University ROMA TRE

MAIN ROLES AND RESPONSIBILITIES

Since 2019	Director of Master second level “La cybersecurity per la protezione dei sistemi di controllo nell’industria 4.0 e nelle infrastrutture critiche”
since 2018	Rector’s delegate for Digital Technological Transfer
From 2008 To 2020	Coordination of Ph.D. programme in Computer Science and Automation
From 2015 To 2019	Vice-president of “Comitato Unico di Garanzia” of ROMA TRE (2015-2019)
Since 2012	Director of MCIPlab, Models for Critical Infrastructure Protection laboratory
2010	Member of the Working group on Critical Infrastructures of Prime Minister Council
2013	Member of the Working group on Cyber Security National Strategies of Prime Minister Council.

SERVICE TO NATIONAL AND INTERNATIONAL COMMUNITY

From 1090 To 1991	Officer in the Italian Airforce
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TEACHING EXPERIENCE

since 1996	Fundamentals of Automatic Control (Bachelor course of Mechanical Engineering, Electronic Engineering, Computer Science Engineering)
since 2005	Automatic Control (Master degree in Mechanical Engineering, Aeronautics Engineering)
Since 2012	Distributed Control for Large Infrastructures (Master degree in Management and Automation Engineering)
From 2001 To 2017	Industrial Automation Control Systems – SCADA (Bachelor course of Automation and Computer Science Engineering)

MAIN RESEARCH EXPERIENCE

2015	SMART ENVIRONMENTS – Valorizzazione della ricerca e crescita del territorio negli ambienti intelligenti. Finanziato dalla Regione Lazio - AVVISO PUBBLICO RELATIVO A PROGETTI DI RICERCA PRESENTATI DA UNIVERSITÀ E CENTRI DI RICERCA – LR 13/2008 – PROJECT COORDINATION – Grant 1500 KEuro
2014	URANIUM – Unified Risk Assessment Negotiation via Interoperability Using Multi-sensor data European Commission – DGJFS Prevention Preparedness and Consequence Management of Terrorism and other Security related Risks CIPS Grant Action 2013. PROJECT COORDINATION – Grant 450 K Euro

2017	ATENA - Advanced tools to assess and mitigate the criticality of ICT components and their dependencies over Critical Infrastructures - Horizon 2020 – Secure Societies – DS-3-2015 – The role of ICT in Critical Infrastructures Protection. SCIENTIFIC COORDINATION. 8000 K Euro.
2012	CockpitCI - Cybersecurity on SCADA: risk prediction, analysis and reaction tools for Critical Infrastructure. FP7-SEC-2011.2.5-1 Cyber attacks against critical infrastructures – Capability Project SCIENTIFIC COORDINATION. 6000 K Euro.
2008	MICIE - Tool for systemic risk analysis and secure mediation of data exchanged across linked CI information infrastructures. FP7-ICT-SEC-2007.1.7 SCIENTIFIC COORDINATION. 6000 K Euro.
2019	RESISTO - RESilience enhancement and risk control platform for communication infraStructure Operators. European Commission. Horizon 2020 – Secure Societies – DS-3-2015 – The role of ICT in Critical Infrastructures Protection. INNOVATION MANAGER. 8000 K Euro.
2012	FACIES - online identification of Failure and Attack on interdependent Critical Infrastructures. Prevention Preparedness and Consequence Management of Terrorism and other Security related Risks CIPS Grant Action 2011. LOCAL COORDINATOR. 200 K Euro.

MAIN AREA OF RESEARCH

The mathematical frameworks and techniques that I have applied include Iterative Learning Control, Nonlinear control, Fuzzy Logic, Bayesian Estimation, Kalman Filtering, Particle Filters, Non-holonomic systems, Dempster-Shafer Theory, Genetic Algorithms, Neural Networks, Complex Networks analysis, Distributed Estimation, MPC. In particular, the following areas I have many published results.

Flexible Robots	In the area of robots with elastic elements I have published several paper about control with nonlinear techniques, iterative learning control (ILC) and cyclic control, in particular showing the feasibility of ILC for such systems with instable zero-dynamics. Some papers have been dedicated to the problem of repositioning showing the existence of iterative algorithms with low complexity. Many experiments have been conducted on the FLEXARM, a two link flexible arm that I have contributed to design and build.
Mobile Robotics	In this field I worked on many problems, ranging from iterative trajectory learning to path planning, from map building to localization problems also in multi-robot environments. Many results have been published using several different techniques. Some remarkable contributions are in the field of simultaneous localization and mapping. I have put some attention into the problem of navigation in structured and unstructured environments with a special interest for the problem of sensor based navigation and sensor fusion. Many techniques derived from Fuzzy Logic, Bayesian Estimation (Kalman Filtering) and Dempster-Shafer theory have been developed and applied to the problem of mapping building and vision based localisation.

Sensor Networks	In this area I have published several works on the problem of localization using innovative algorithms and extending some previous results. The techniques that have been used range from interlaced Kalman filtering to interagent particle filters, and some new results have been found using shadow edges.
Complex Networks	I have been interested in Complex Networks for modelling purposes and I have researched many application also to the path planning problem. An important result has been found with the application of complex networks theory into evolutionary computation showing the particular performances of genetic algorithm over structured spaces. Many applications have been found in the mobile robot localization problem.
Smart Buildings, Smart Grids	In this field I have studied energy problems and found many results regarding fault detection and anomaly detection. Some work has been done using Model Predictive Control applied with a distributed/decentralized philosophy to the temperature control problem for a set of communicating rooms.
Critical Infrastructures Protections	I have been among the first to work in this sector involving modelling and control problems. I have published several papers on main conferences and Journals in the field and I have contributed to the developing of a simulation model, the CISIApro approach, able to evaluate cascading effects in a network of infrastructures.

ADDITIONAL INFORMATION

Publications List of Journal Papers

- Masucci D, Foglietta C, Panzieri S, Pizzuti S. Enhancing the smart building supervisory system effectiveness. *Intelligent Build Int* 2021.
- Faramondi L, Oliva G, Panzieri S, Pascucci F, Schlueter M, Munetomo M, Setola R. Network structural vulnerability: A multiobjective attacker perspective. *IEEE Trans Syst Man Cybern Syst* 2019;49(10):2036-49.
- Oliva G, Panzieri S, Setola R, Gasparri A. Gossip algorithm for multi-agent systems via random walk. *Syst Control Lett* 2019;128:34-40.
- Foglietta C, Masucci D, Palazzo C, Santini R, Panzieri S, Rosa L, Cruz T, Lev L. From detecting cyber-attacks to mitigating risk within a hybrid environment. *IEEE Syst J* 2019;13(1):424-35.
- Corbò G, Foglietta C, Palazzo C, Panzieri S. Smart behavioural filter for industrial internet of things: A security extension for PLC. *Mobile Networks Appl* 2018;23(4):809-16.
- Adamsky F, Aubigny M, Battisti F, Carli M, Cimorelli F, Cruz T, Di Giorgio A, Foglietta C, Galli A, Giuseppe A, Liberati F, Neri A, Panzieri S, Pascucci F, Proenca

- J, Pucci P, Rosa L, Soua R. Integrated protection of industrial control systems from cyber-attacks: The ATENA approach. *Int J Crit Infrastruct Prot* 2018;21:72-82.
7. Faramondi L, Setola R, Panzieri S, Pascucci F, Oliva G. Finding critical nodes in infrastructure networks. *Int J Crit Infrastruct Prot* 2018;20:3-15.
 8. Miciolino EE, Setola R, Bernieri G, Panzieri S, Pascucci F, Polycarpou MM. Fault diagnosis and network anomaly detection in water infrastructures. *IEEE Des Test* 2017;34(4):44-51.
 9. Oliva G, Setola R, Panzieri S. Critical clusters in interdependent economic sectors: A data-driven spectral clustering analysis. *Eur Phys J : Spec Top* 2016;225(10):1929-44.
 10. Oliva G, Setola R, Panzieri S, Pascucci F. Localization of networks with presence and distance constraints based on 1-hop and 2-hop mass-spring optimization. *ICT Express* 2016;2(1):19-22.
 11. Oliva G, Panzieri S, Pascucci F, Setola R. Sensor networks localization: Extending trilateration via shadow edges. *IEEE Trans Autom Control* 2015;60(10):2752-5.
 12. Moretti F, Pizzuti S, Panzieri S, Annunziato M. Urban traffic flow forecasting through statistical and neural network bagging ensemble hybrid modeling. *Neurocomputing* 2015;167:3-7.
 13. Foglietta C, Panzieri S, Pascucci F. Algorithms and tools for risk/impact evaluation in critical infrastructures. *Stud Comput Intell* 2015;565:227-38.
 14. Carli M, Panzieri S, Pascucci F. A joint routing and localization algorithm for emergency scenario. *Ad Hoc Netw* 2014;13(PART A):19-33.
 15. Oliva G, Panzieri S, Setola R. An amendment to distributed synchronization under uncertainty: A fuzzy approach. *Fuzzy Sets Syst* 2014;235:104-6.
 16. Di Pietro A, Panzieri S. Taxonomy of SCADA systems security testbeds. *Int J Crit Infrastruct* 2014;10(3-4):288-306.
 17. Santini R, Foglietta C, Panzieri S. Evidence theory for cyber-physical systems. *IFIP Advances in Information and Communication Technology* 2014;441:95-109.
 18. Oliva G, Panzieri S, Setola R. Discrete-time linear systems with fuzzy dynamics. *J Intelligent Fuzzy Syst* 2014;27(3):1129-41.
 19. Oliva G, Panzieri S, Priolo A, Ulivi G. Characterising failures and attacks in average consensus. *Intern J Syst Control Comm* 2014;6(1):1-19.
 20. Panzieri S, Pascucci F, Sciavicco L, Setola R. Distributed cooperative localization. *J Inf Technol Res* 2013;6(3):49-67.
 21. Digioia G, Panzieri S. Homeland situation awareness through mining and fusing heterogeneous information from intelligence databases and field sensors. *Int J Syst Syst Eng* 2013;4(3-4):190-210.
 22. Foglietta C, Panzieri S, Macone D, Liberati F, Simeoni A. Detection and impact of cyber attacks in a critical infrastructures scenario: The CockpitCI approach. *Int J Syst Syst Eng* 2013;4(3-4):211-21.

23. Oliva G, Panzieri S, Setola R. Distributed consensus under ambiguous information. *Int J Syst Syst Eng* 2013;4(1):55-78.
24. Digioia G, Foglietta C, Oliva G, Panzieri S. Aware online interdependency modelling via evidence theory. *Int J Crit Infrastruct* 2013;9(1-2):74-92.
25. Oliva G, Panzieri S, Setola R. Distributed synchronization under uncertainty: A fuzzy approach. *Fuzzy Sets Syst* 2012;206:103-20.
26. Gasparri A, Fiorini F, Di Rocco M, Panzieri S. A networked transferable belief model approach for distributed data aggregation. *IEEE Trans Syst Man Cybern Part B Cybern* 2012;42(2):391-405.
27. Oliva G, Panzieri S, Setola R. Fuzzy dynamic input-output inoperability model. *Int J Crit Infrastruct Prot* 2011;4(3-4):165-75.
28. Oliva G, Panzieri S, Setola R. Agent-based input-output interdependency model. *Int J Crit Infrastruct Prot* 2010;3(2):76-82.
29. Gasparri A, Panzieri S, Priolo A. A fitness-sharing based genetic algorithm for collaborative multi-robot localization. *Intelligent Serv Rob* 2010;3(3):137-49.
30. Gasparri A, Panzieri S, Pascucci F, Ulivi G. An interlaced extended kalman filter for sensor networks localisation. *Int J Sens Netw* 2009;5(3):164-72.
31. De Porcellinis S, Panzieri S, Setola R. Modelling critical infrastructure via a mixed holistic reductionistic approach. *Int J Crit Infrastruct* 2009;5(1-2):86-99.
32. Gasparri A, Panzieri S, Pascucci F. A spatially structured genetic algorithm for multi-robot localization. *Intelligent Serv Rob* 2009;2(1):31-40.
33. Panzieri S, Pascucci F, Setola R. Simultaneous localisation and mapping of a mobile robot via interlaced extended kalman filter. *Int J Model Ident Control* 2008;4(1):68-78.
34. Panzieri S, Setola R. Failures propagation in critical interdependent infrastructures. *Int J Model Ident Control* 2008;3(1):69-78.
35. De Porcellinis S, Setola R, Panzieri S, Ulivi G. Simulation of heterogeneous and interdependent critical infrastructures. *Int J Crit Infrastruct* 2008;4(1-2):110-28.
36. Gasparri A, Panzieri S, Pascucci F, Ulivi G. Monte carlo filter in mobile robotics localization: A clustered evolutionary point of view. *J Intell Rob Syst Theor Appl* 2006;47(2):155-74.
37. Panzieri S, Pascucci F, Ulivi G. An outdoor navigation system using GPS and inertial platform. *IEEE ASME Trans Mechatron* 2002;7(2):134-42.
38. Oriolo G, Panzieri S, Ulivi G. Learning optimal trajectories for non-holonomic systems. *Int J Control* 2000;73(10):980-91.
39. Oriolo G, Panzieri S, Ulivi G. An iterative learning controller for nonholonomic mobile robots. *Int J Rob Res* 1998;17(9):954-70.
40. Lucibello P, Panzieri S. Application of cyclic control to a two-link flexible arm. *Automatica* 1998;34(8):1025-9.
41. Lucibello P, Panzieri S. Cyclic control of linear systems with application to a flexible arm. *IEE Proc Control Theory Appl* 1998;145(1):19-24.

42. Lucibello P, Panzieri S. Cyclic control of robot arms. *Kybernetika* 1997;33(1):87-102.
43. Lucibello P, Panzieri S. Experiments on output tracking with internal stability by learning for a one-link flexible arm. *Automatica* 1997;33(11):2065-9.
44. Lucibello P, Panzieri S, Ulivi G. Repositioning control of a two-link flexible arm by learning. *Automatica* 1997;33(4):579-90.
45. De Luca A, Panzieri S. End-effector regulation of robots with elastic elements by an iterative scheme. *Int J Adapt Control Signal Process* 1996;10(4-5):379-93.
46. De Luca A, Panzieri S. An iterative scheme for learning gravity compensation in flexible robot arms. *Automatica* 1994;30(6):993-1002.
47. Luca AD, Panzieri S. Learning gravity compensation in robots: Rigid arms, elastic joints, flexible links. *Int J Adapt Control Signal Process* 1993;7(5):417-33.

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